

GISERA | Gas Industry Social and Environmental Research Alliance

Baseline seismic monitoring of the Canning Basin

Interim Reports 2 & 3

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We sincerely thank the Earth Imaging and Observation team at the Geological Survey of Western Australia for installing and maintaining the seismic stations and making the data available. We also thank Geoscience Australia for maintaining the interface for providing the data openly. Former CSIRO scientist Dr Yuqing Chen is thanked for contributing to the first fieldwork along with GSWA team for the installation of the sites. We also than Dr Andrew King of CSIRO for critically reviewing this report.

Summary

The combined interim report provides an update on activities related to Task 2 (Establishment of a Data Centre and Detection Workflow) and Task 3 (Development of the Seismicity Publication Platform) of the baseline seismic monitoring project in the Canning Basin.

For Task 2, we developed and deployed a fully operational data processing system that automatically retrieves seismic waveform data from the GSWA network, as well as from national and international repositories. Using recent machine learning-based detection tools such as EQTransformer and PhaseNet, the system can detect, pick, and locate small-magnitude seismic events across the region. Events are automatically processed and catalogued, with key information such as origin time, location, magnitude, and depth extracted and stored. ML-based methods such as EQTransformer and PhaseNet have demonstrated improved sensitivity to low SNR events and reduced false positives compared to traditional STA/LTA approaches (Zhu & Beroza, 2019).

Task 3 focused on making these results accessible through a user-friendly, web-based interface. A prototype publication platform was built using open source platform Streamlit, allowing users to view earthquake locations on interactive maps, query event metadata, and download catalogues. The platform includes both a heat map and cluster map view of events, with search filters by time, magnitude, and depth. The system is lightweight, does not require dedicated hardware, and has been demonstrated successfully on standard desktop machines.

Together, these two components form the core of the baseline seismic monitoring capability for the region. The workflows established here will allow for ongoing tracking of background seismicity and form the reference against which any future changes in seismic activity can be assessed.

Publication Dissemination Platform

Task 3 involved the development of a public-facing dissemination platform using Streamlit, an open-source Python framework that enables interactive applications from Python scripts. This web interface, which is currently in a prototype stage, includes:

- A heat map for event density.
- A cluster map with zoom functionality.
- A downloadable, filterable event catalogue with fields for time, magnitude, depth, and coordinates.

The platform is lightweight and can be operated on standard desktop hardware. The goal was to provide public access to the seismicity catalogue generated in Task 2, in a transparent and accessible format.

The interface consists of two main map panels (Figure 1). The first panel displays a heat map showing the spatial density of detected events. This provides an intuitive visual summary of seismic activity across the selected region. The second panel presents the same events in a clustered format, where nearby events are grouped to improve readability when zoomed out. Both maps use OpenStreetMap, which is an open-source data as the base layer and support zoom and pan functionality.

Below the maps, a tabular view (Figure 1) lists all detected events, including event ID, time, magnitude, depth, and coordinates. This table can be filtered using input boxes in the left-hand panel, allowing users to constrain events by magnitude, depth, and date range. The table is downloadable in plain text (.csv) format.

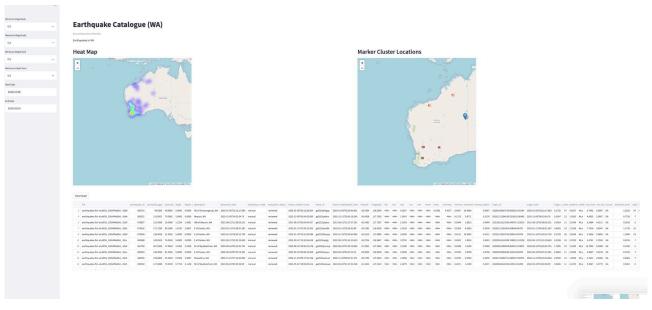


Figure 1 Screenshot of the Streamlit-based interface showing the earthquake heat map (left) and cluster map (right). The heat map highlights areas with high concentrations of detected events, while the cluster map groups closely spaced events for easier visualisation. The lower panel of the interface displays a searchable, filterable event catalogue. Users can download the catalogue and apply custom filters based on time, magnitude, and depth.

The bottom panel of the interface can also be expanded to full screen using a resize button (Figure 2), allowing for detailed inspection of the earthquake catalogue mainly for the specialist audience e.g., earth scientists.

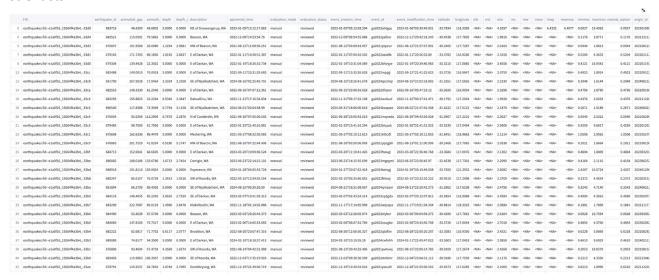


Figure 2 The tabular event panel can be maximised for easier viewing using the resize button in the top-right corner. The table is showing technical details of each earthquake tailored for the specialists.

The left column of the interface (Figure 3) provides a search box for magnitude, depth, date ranges, where the catalogue can be filtered easily.

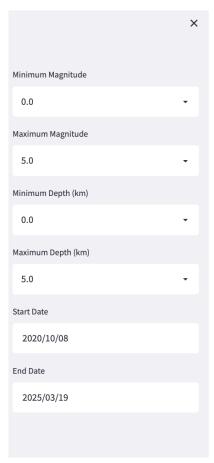


Figure 3: Search box for filtering based magnitude, depth, and date ranges.

Both maps can be interactively zoomed in & out. The heat map representation of the earthquake data updates itself, according to the zoom level and also the number of earthquakes and their magnitudes within the visualisation window (Figure 4).

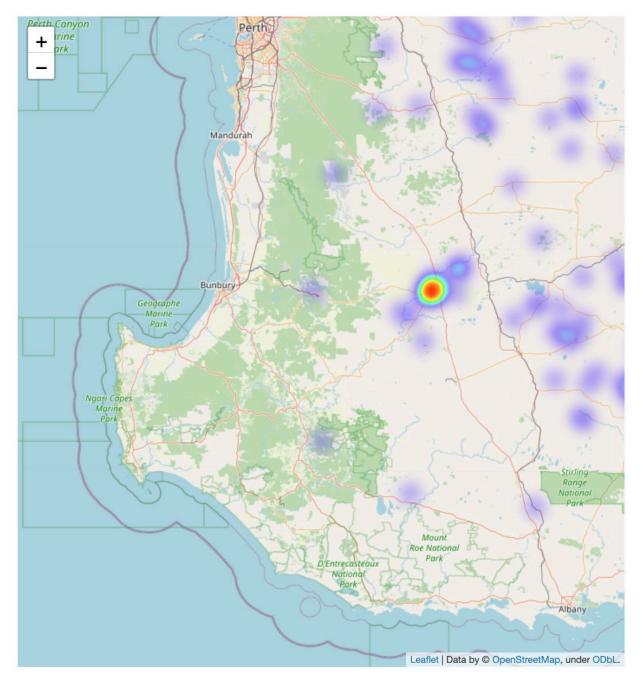


Figure 4: Zoomed-in version of the earthquake heat map.

The cluster map can be also interactively zoomed in and out to query earthquake information. By clicking blue pins corresponding to each earthquake, location coordinates, earthquake magnitude, hypocentre depth and the origin time can be obtained (Figure 5).

Marker Cluster Locations

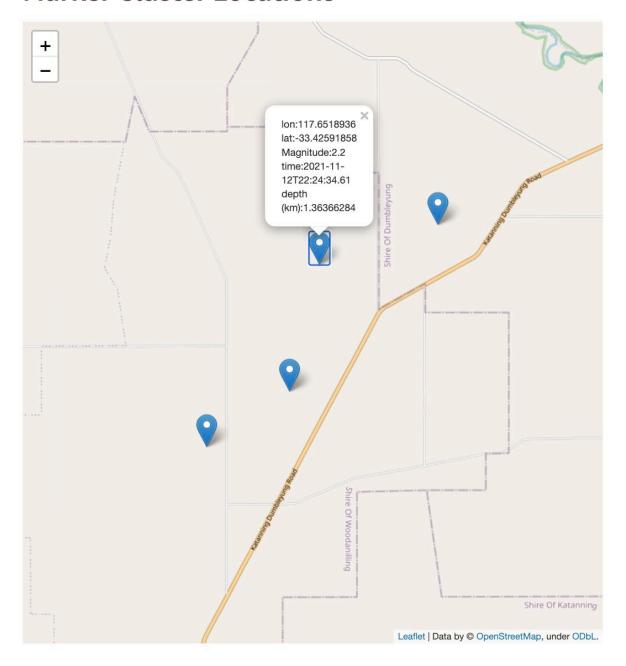


Figure 5: Example of metadata window triggered by clicking on an event marker in the cluster map. In the meta window, the spatial coordinates, hypocentre (depth), origin time (UTC-Coordinated Universal Time) and the magnitude of the selected event is shown.

In addition to its functionality, the platform is extremely lightweight and can be run on a desktop machine with minimal computational resources.

Conclusion

We designed a modern inter-active public information dissemination platform using purely opensource tools. This new platform does not require any ongoing fees from the server side, and is lightweight, meaning it requires minimum resources to be operational. The training session was delivered to the scientists of GSWA, and the platform will be transferred to their servers, once the infrastructure at their end becomes ready.

Seismicity

We analysed seismic data collected by GSWA and Geoscience Australia between July 2023 and July 2024. Data prior to this period was not used due to issues such as firmware errors (e.g., internal clock drift) and data loss from Tropical Cyclone Ellie (late December 2022 – early January 2023). These issues have now been retrospectively corrected by GSWA, and we will include an Annexure showing the list of the detected events by using the currently corrected data, post the completion of this project.

A map showing seismic station locations and operating mines is provided in Figure 6. A total of **9 events** were detected between July 2023 and July 2024 (see Table 1). Most detected events are not spatially correlated with mining/quarry operations, suggesting a natural origin. One event is located near an active quarry site with a magnitude of 2.4 and depth of \sim 9.5 km. However, a depth of \sim 9.5 km is atypical for quarry blasting, which occurs at much shallower depths (typically less than 1 km). To the south of the array, no events were detected, likely due to decreased network sensitivity outside the station perimeter.

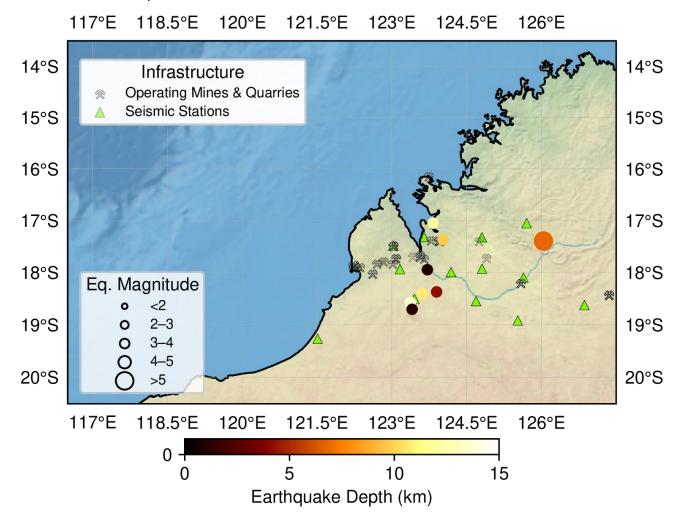


Figure 6 Map of seismic stations and detected events between July 2023 and July 2024. Operating mines and quarries are shown along with the seismic stations used in this study.

Origin Time (UTC)	Latitude (DD)	Longitude (DD)	Depth (km)	Magnitude (MI)
2023-09-21T06:17:11.730000Z	-18.402	123.612	11.375	2.7
2023-10-21T01:51:17.040000Z	-17.068	123.830	12.757	2.5
2023-11-18T03:25:02.240000Z	-18.575	123.373	13.832	2.1
2023-11-22T04:47:23.190000Z	-17.945	123.714	0.943	2.1
2023-11-28T13:01:29.680000Z	17.031	123.823	12.212	2.3
2023-12-12T15:56:24.430000Z	-17.394	126.042	6.831	4.2
2024-02-27T14:59:53.630000Z	-18.704	123.407	1.379	2.3
2024-03-19T08:23:52.450000Z	-18.371	123.898	4.263	2.4
2024-06-03T21:04:53.120000Z	-17.368	124.029	9.522	2.4

Table 1: List of the detected and located events between July 2023 and July 2024 in this project.

Yearly Seismicity (2010-2020)

We re-examined the historical earthquake catalogue from Geoscience Australia (GA) for 2010–2020 prior to the installation of the stations (Figures 7-9). As expected, the number of recorded events is low, which likely reflects limited detection capability due to sparse station coverage.

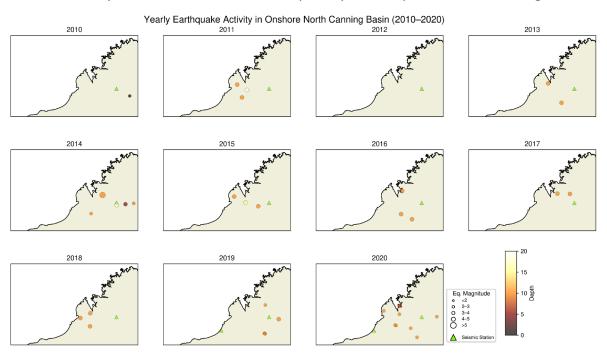


Figure 7: Yearly seismicity from 2010–2020 detected by the GA network. Green triangles show the seismic stations, with only one station operating between 2010 and 2018 and another one added later. Note that the plots do not include the offshore earthquakes.

Yearly Earthquake Depth Distributions Onshore North Canning Basin (2010–2020)

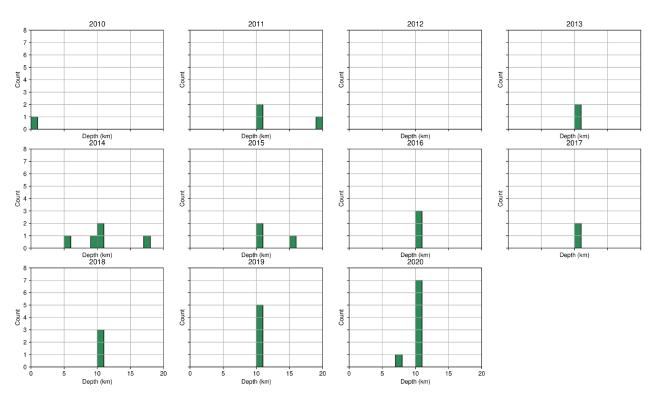


Figure 8: Depth seismograms for 2010 – 2020 seismic events. Note that the plots do not include the offshore earthquakes.

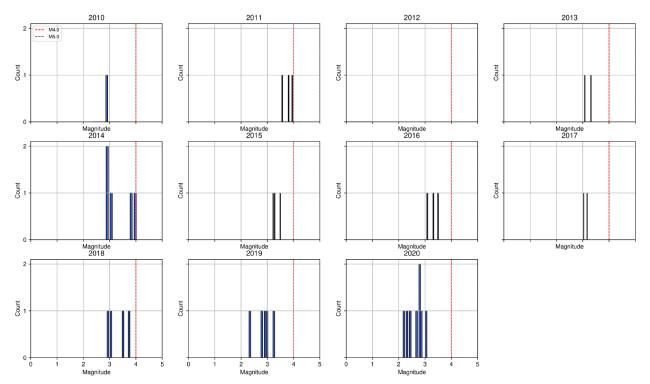


Figure 9: Magnitude distribution for 2010-2020 seismic events. Note that the plots do not include the offshore earthquakes. Vertical red line marks the magnitude 4 events.

Comparison with Geoscience Australia Catalogue

We compared the CSIRO catalogue with GA's for the same period and area. The catalogues show high spatial overlap. However, event depth estimates diverge substantially.

GA often reports depths clustered at 10 km, which is a default assignment when depth is poorly constrained. CSIRO's depth estimates are based on the continent-specific seismic velocity model developed by Chen et al. (2023) for Vs and AusRem (Salmon et al. 2013) for Vp, leading to reduced uncertainty and a more realistic distribution compared to GA's standard default-depth assignments

GA's standard workflow is based on deterministic detection algorithms. This is mainly due to the operational requirements, where ML based methods can be significantly more computationally intensive and time-consuming. Meanwhile, ML based methods are proven to be much more robust in other studies (Zhu & Beroza, 2019; Mousavi et al., 2020). In Figure 10, we show earthquakes from CSIRO and GA catalogues. Overall, the catalogues have a significant amount of similarity in the detected events (CSIRO: 9 and GA: 7) and general spatial locations. However, the depth distribution of the events for the catalogues have striking differences. The depth estimations from CSIRO used the velocity model of Chen et al. (2023) and AusREM (Salmon et al. 2013), which are specific for Australia resulted in lower uncertainty in depth estimates.

Here in our approach, we have better estimates of the depth which has a wider -range, whereas several of the GA depths are around 10 km, which denotes higher uncertainty. Geoscience Australia commonly assigns a default depth of 10 km in the absence of well-constrained solutions, which may contribute to the clustering of reported depths like the other agencies (USGS).

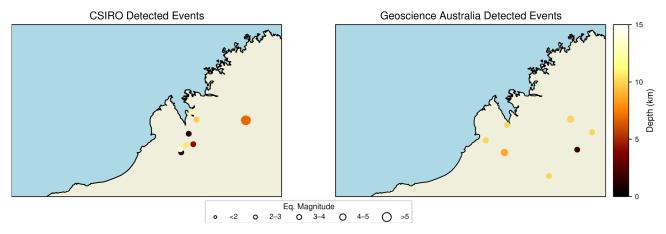


Figure 10: Detected events by this project and Geoscience Australia's catalogue for the same time period (2023-2024) and geographic area. Most of the earthquake depths of Geoscience Australia are around 10 km indicating high uncertainty as also seen in reported depths from other agencies, CSIRO's catalogue exhibits greater depth variation with most of them close to the surface.

Conclusion

The newly deployed GSWA stations have improved regional detection capability since 2021. Hence the number of detected events has increased accordingly. CSIRO and GA catalogues generally agree in event location, but CSIRO's depth estimates are more robust due to use of a continent-wide CSIRO crustal seismic model (Chen et al., 2023). Overall, we argue that there is no observable seismic activity increase during the analysis period.

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